

# Intelligent Screwdriver



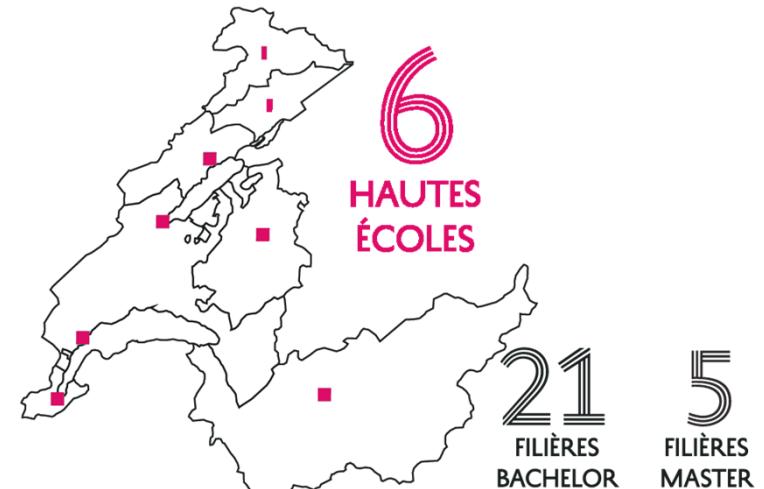
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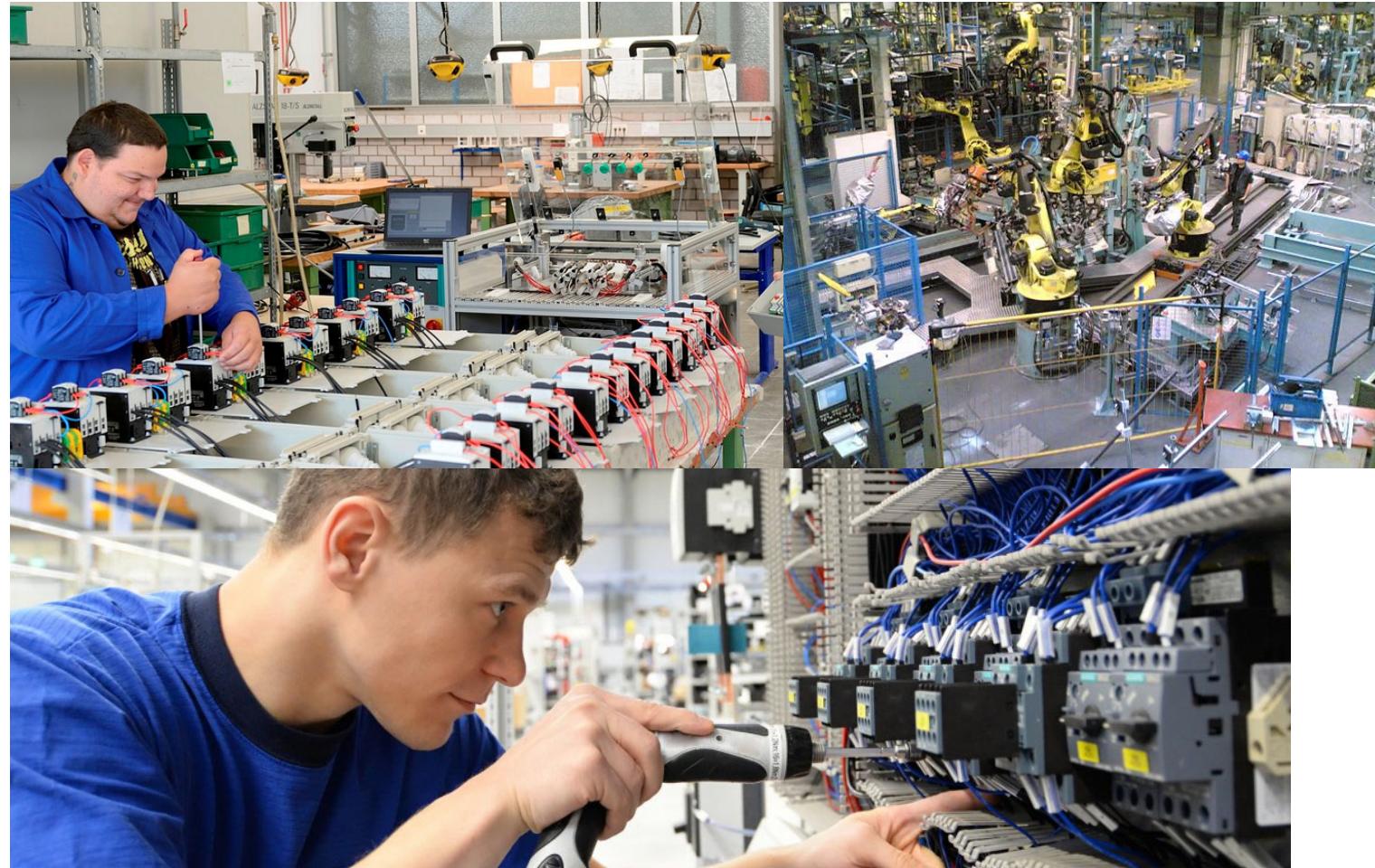


Georg Wälder &  
Michel Lauria – hepia (GE)  
Christophe Besson - HEIG-VD  
Oliver Hüsser - HE-ARC



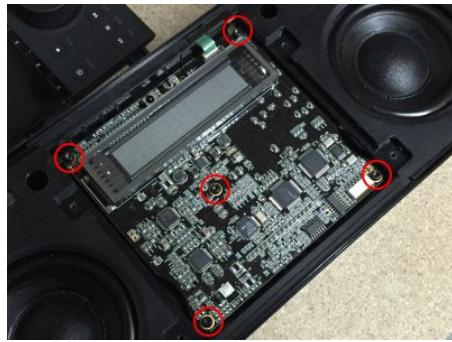
# Contexte du projet

## Industrie 4.0



# Camera & Pattern recognition

## 1. Identification de la zone de travail— position de vissage



## 3. Configuration (torque, #tours)

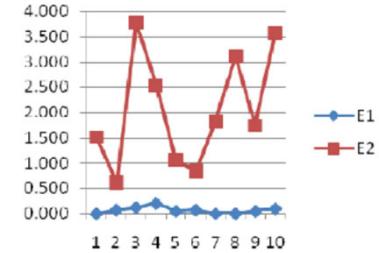
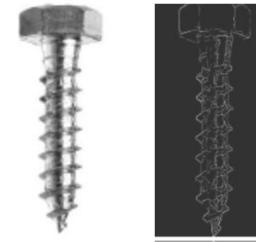


## 4. Qualité : Protocol de l'opération: Paramètres, mesures torque, photo & vidéo

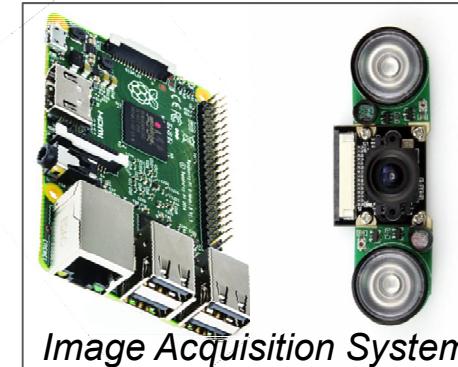
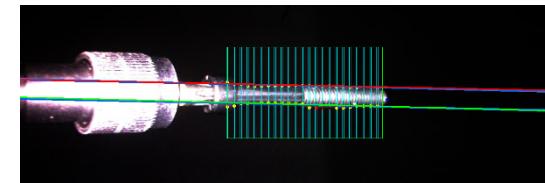
Microsoft Excel - Wedel1.xls

	Eingänge	Ausgänge	Aufzeichnung
1 Temperatur		JF Heizung	
2 Schleife	25	JF Grundheiz	Start
3 Aussen	12		
4 Raum	25		
5 Pfeil	45	DrehrichtungWP2	
6 Bilder	5	Heizdruck-WP2	Reserv A E7
7 WPS		Heizdruck-WP2	Stop
8 WPS		Wärme reg-WP1	
9 Reserv	25	Strömung-WP2	gestoppt 0°/10°
10 Reserv			

## 2. Identification de la vis programmation des paramètres



Diameters, longueurs, filetage, matière...



## 1. Torque transmission & Control: New Clutch concept :

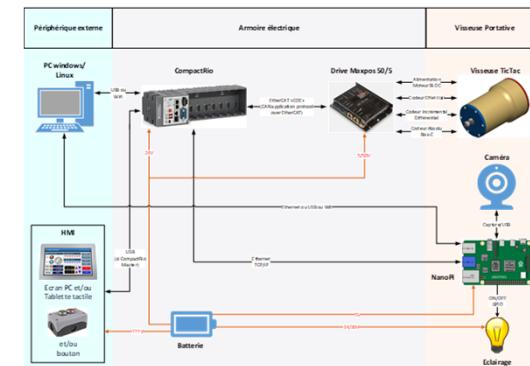
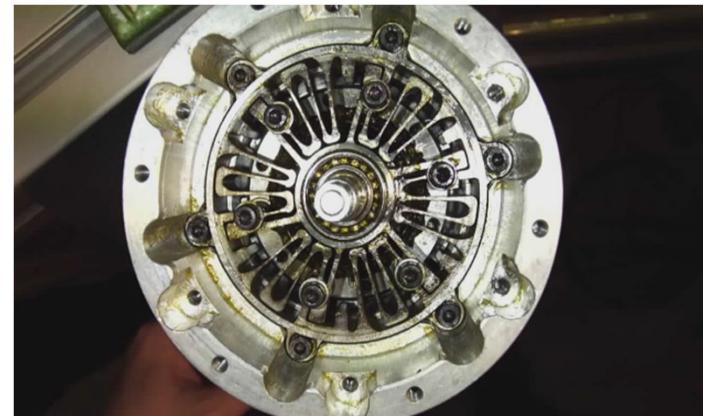
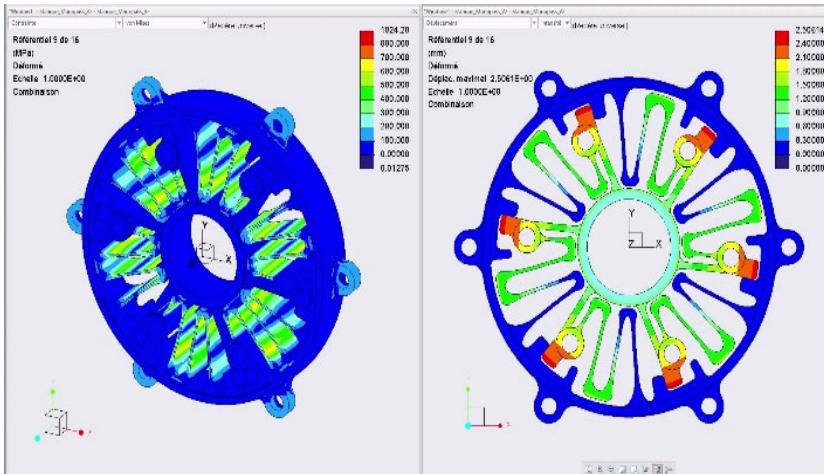
- Mechanical design of clutch : “wrap-spring”
- Embedded controller: averages screwing torque precision < 3% , and without overdriving
- Screwing speed (for 30 mm long, M6 screw) < 0.5 sec, with screw & place identification <= 0.7 sec

## 2. Vision system & Machine Learning

- compact(<200g) low-power(<5W) prototype vision system (camera, light)
- machine learning – neural networks - able to identify screw model and location with an accuracy about 99 %

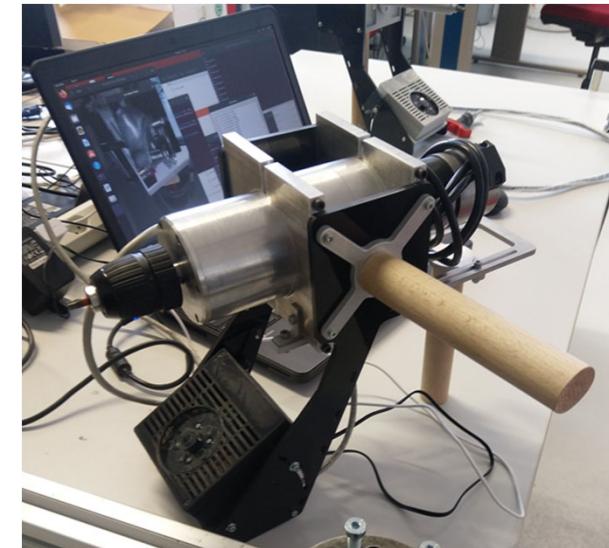
# Concept mécanique

- Flexible Hinges, Control algorithm



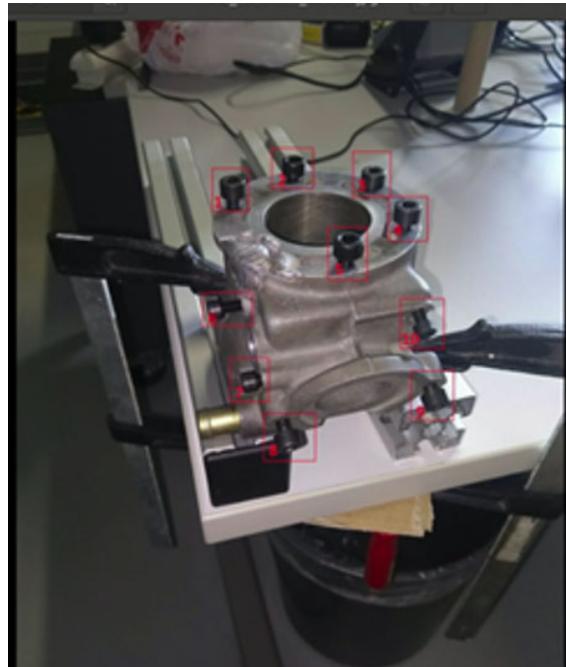
## Vision module

- Prototype (Fabrication additive) :
- vision intégré (camera Basler) & light
- Processor : NanoPi NEO3
- Poids 224g (possible de réduire : suppression Ethernet connecteur , optimiser boite)

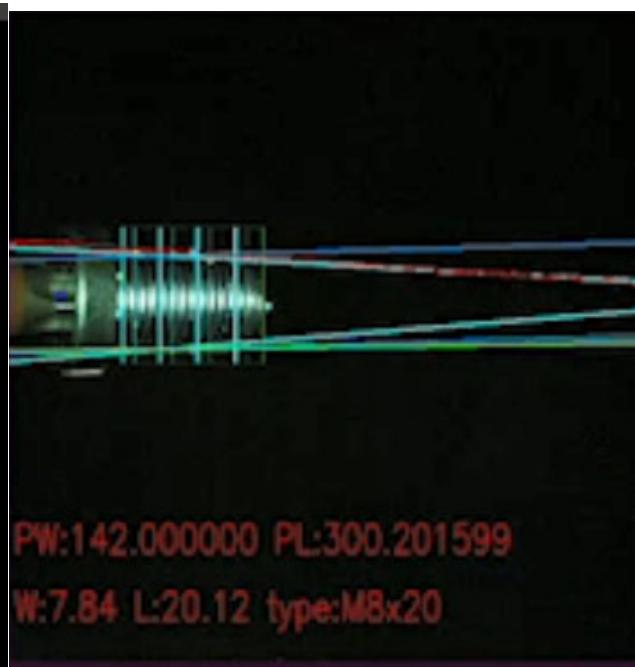


# Identification

Teach - in



Identification vis



Identification lieu



# Evaluation de la performance

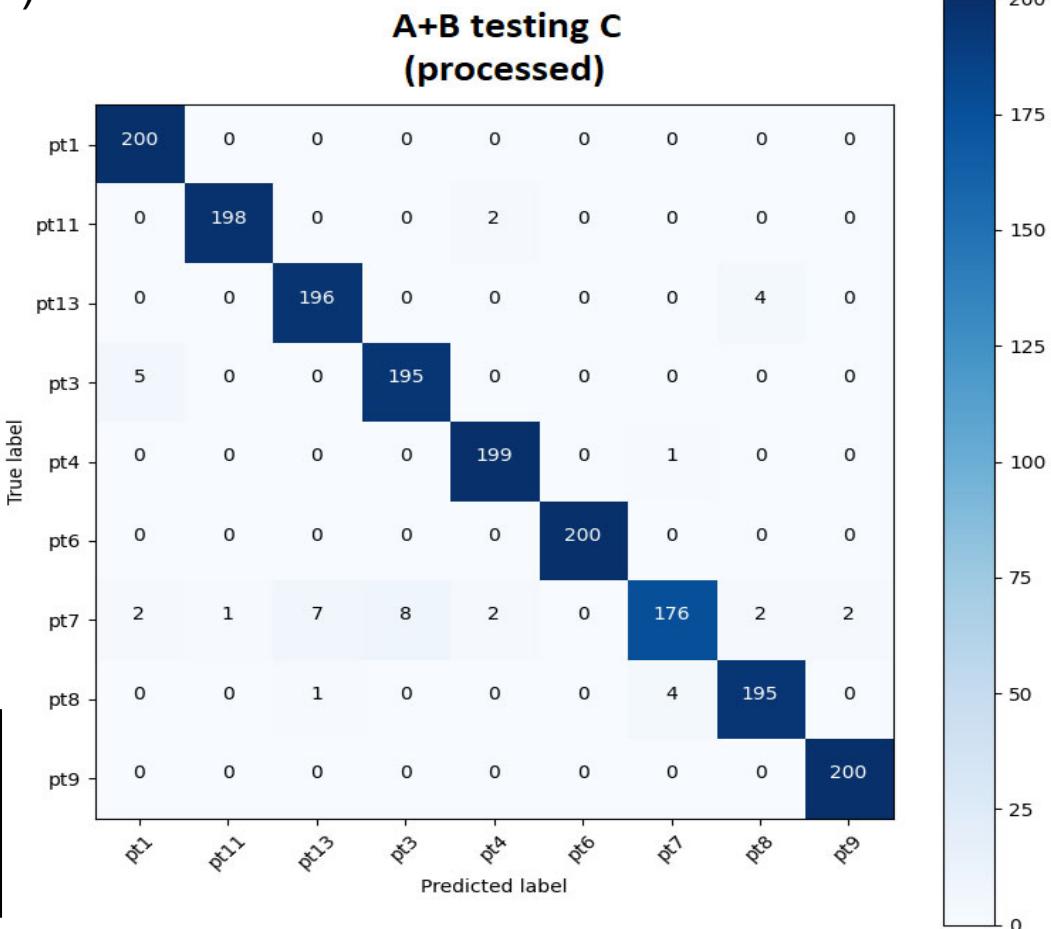
Results : Detection of screwing position @ PC-Box@home

Based on 3 samples A,B,C , combining 2 to make prediction of 3<sup>rd</sup>  
( which not used for model)



f=10mm	A+B test C
<b>Précision (moyenne)</b>	97.70%
<b>Rappel (moyenne)</b>	97.70%
<b>F-mesure (moyenne)</b>	97.60%

With applied correction of histograms	
Right positif = 176	
False positifs = 1 + 4 = 5	
Total positifs = 176 + 5 = 181	
Précision = 176/181 = 97.2%	



# Evaluation de la performance

Detection de la position des vis

Case 2 & 3 : Motor &

valve



# Résultats

- Protocol : Labview => excel

## Visseuse TicTac 2

Opérateur:	Operateur
Date:	24.02.2022
Heure:	15:36
Vitesse:	400
Accélération:	1000

- #vis
- Longueur
  - Diamètre
  - Position
  - Couple

### Recette

NB Vis	TicTac Consigne				
	Diamètre [mm]	Longueur [mm]	Position	Consigne Couple [Nm]	
1	8	10	0	3	

### Vision

NB Vis	Système de détection					
	Diamètre [mm]	Longueur [mm]	Position	Couple Max [Nm]	Diamètre Absolu [mm]	Longueur Absolu [mm]
1	8	10	0	3	8	100

## Prochaines étapes:

### Cherche des investisseurs

- Production
- Distribution
- Compléter gamme produit

**DEMO: GE-Innovation**

# Resumé

